

Hildeberto Jardón Kojakhmetov

Curriculum Vitae

September 3, 2018

Personal information

Name	Hildeberto Jardón Kojakhmetov
Date and place of birth	6 May 1985, México City, México.
Nationality	Mexican
Address	Technical University of Munich (TUM) Faculty of Mathematics Boltzmannstr. 3 85748 Garching bei München, Germany
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Education

PhD	Aug. 2011 - Jun. 2015	Mathematics (Dynamical Systems), University of Groningen, Groningen, The Netherlands. Thesis: “Classification of constrained differential equations embedded in the theory of slow fast systems” Supervisors: Prof. Dr. Henk W. Broer and Prof. Dr. Gert Vegter.
MSc	Aug. 2008 - Sept. 2010	Automatic Control, CINVESTAV, México City, México. Thesis: “Discrete control of Hill systems” (in Spanish).
BSc	Aug. 2002 - Jul. 2007	Mechatronics Engineering, UPIITA-IPN, México City, México. Thesis: “Development, modeling and control of a biped humanoid robot” (in Spanish).

Employment

- Mar. 2018 - Feb. 2019 *Postdoctoral researcher*
Technical University Foundation Fellowship
Technical University of Munich, Germany
Supervisor: Prof. Dr. Christian Kuehn
Research topic: Slow-fast consensus networks
- Jul. 2017 - Mar. 2018 *Postdoctoral researcher* at GBB, University of Groningen,
The Netherlands
Supervisor: Prof. Dr. Bert Poolman
Research topic: development of mathematical and computational
models for a synthetic cell
- Jul. 2015 - Jun. 2017 *Postdoctoral researcher* at ENTEG, University of Groningen,
The Netherlands
Supervisor: Prof. Dr. ir. Jacquelin M.A. Scherpen
Research topic: Stabilization of slow-fast systems at
non-hyperbolic points
- Sept. 2009 - Jul. 2011 *Lecturer* at the National Polytechnic Institute,
México City, México.
- Sept. 2007 - Jul. 2008 *Designer* at NISSAN Mexicana, Toluca, México.
- Nov. 2006 - Feb. 2007 *Designer* at Bosch-Rexroth, México City, México.

Publications

Peer-reviewed Journals

- (J.1) H. Jardón-Kojakhmetov, J. M. Scherpen, and D. del Puerto-Flores, “Stabilization of a class of slow-fast Systems at non-hyperbolic points,” *accepted in Automatica*, 2018.
- (J.2) H. Jardón-Kojakhmetov and J. M. Scherpen, “Improving the region of attraction of a non-hyperbolic point in slow-fast systems with one fast variable,” *IEEE Control Systems Letters*, vol. 2, no. 2, pp. 403–408, 2018¹.
- (J.3) H. Taghvafard, H. Jardón-Kojakhmetov, and M. Cao, “Parameter-robustness analysis for a biochemical oscillator model describing the social-behaviour transition phase of myxobacteria,” *Proceedings of the Royal Society of London A: Mathematical, Physical and Engineering Sciences*, vol. 474, no. 2209, 2018.
- (J.4) H. Jardón-Kojakhmetov and J. M. A. Scherpen, “Model order reduction and composite control for a class of slow-fast systems around a non-hyperbolic point,” *IEEE Control Systems Letters*, vol. 1, no. 1, pp. 68–73, 2017².

¹The contents of this paper were also selected by CDC 57 (2018) Program Committee for presentation at the Conference

²The contents of this paper were also selected by CDC 56 (2017) Program Committee for presentation at the Conference

- (J.5) P. Ramazi, H. Jardón-Kojakhmetov, and M. Cao, “Limit sets within curves where trajectories converge to,” *Applied Mathematics Letters*, vol. 68, pp. 94 – 100, 2017.
- (J.6) H. Jardón-Kojakhmetov, H. W. Broer, and R. Roussarie, “Analysis of a slow–fast system near a cusp singularity,” *Journal of Differential Equations*, vol. 260, no. 4, pp. 3785–3843, 2016.
- (J.7) J. Collado and H. Jardón-Kojakhmetov, “Vibrational Stabilization by Reshaping Arnold Tongues: A Numerical Approach,” *Applied Mathematics*, vol. 7, pp. 2005 – 2020, 2016.
- (J.8) H. Jardón-Kojakhmetov, “Formal normal form of Ak slow–fast systems,” *Comptes Rendus Mathematique*, vol. 353, no. 9, pp. 795–800, 2015.
- (J.9) X. Liu and H. Jardón-Kojakhmetov, “Bifurcations of a non-gravitational interaction problem,” *Applied Mathematics and Computation*, vol. 251, pp. 253–257, 2015.
- (J.10) H. Jardón-Kojakhmetov and H. W. Broer, “Polynomial normal forms of constrained differential equations with three parameters,” *Journal of Differential Equations*, vol. 257, no. 4, pp. 1012–1055, 2014.

Preprints

- (P.1) H. Taghvafard, H. Jardón-Kojakhmetov, P. Szmolyan, and M. Cao, “Slow-fast analysis of a biochemical oscillator describing the behaviour of myxobacteria,” 2017. (to be submitted)

Peer-reviewed Conference Proceedings

- (C.1) H. Jardón-Kojakhmetov, J. M. A. Scherpen, and D. del Puerto-Flores, “Nonlinear adaptive stabilization of a class of planar slow-fast systems at a non-hyperbolic point,” in *2017 American Control Conference (ACC)*, pp. 2441–2446, May 2017.
- (C.2) H. Jardón-Kojakhmetov and J. M. A. Scherpen, “Stabilization of a planar slow-fast system at a non-hyperbolic point,” in *22nd International Symposium on Mathematical Theory of Networks and Systems*, pp. 602 – 607, June 2016.
- (C.3) H. Jardón-Kojakhmetov, M. Muñoz-Arias, and J. M. A. Scherpen, “Model reduction of a flexible-joint robot: a port-Hamiltonian approach,” *IFAC-PapersOnLine*, vol. 49, no. 18, pp. 832 – 837, 2016. 10th IFAC Symposium on Nonlinear Control Systems NOLCOS 2016.
- (C.4) R. Martínez-Martínez, H. Jardón-Kojakhmetov, J. A. Leon, and G. Fernández-Anaya, “Estabilización de Redes Complejas Fraccionarias de Sistemas de Lorenz y Sistemas de Chen,” 2009.

Conference Abstracts

- (A.1) Hadi Taghvafard, H. Jardón-Kojakhmetov and Ming Cao. Analysis of a biochemical oscillator model describing the developmental stage of myxobacteria, Benelux Meeting, 2017.
- (A.2) H. Jardón-Kojakhmetov, M. Muñoz-Arias and Jacquelin M.A. Scherpen, *Slow-fast Port-Hamiltonian mechanical systems*, Benelux meeting 2017.
- (A.3) H. Jardón-Kojakhmetov and Jacquelin M.A. Scherpen, *Stabilization of planar slow-fast systems at a non-hyperbolic point*, Benelux meeting 2016.

- (A.4) H. Jardón-Kojakhmetov, M. Muñoz-Arias and Jacquelin M.A. Scherpen, *Control of a flexible-joint manipulator with only position measurements: a port-Hamiltonian approach*, Benelux meeting 2016.

Invited Talks

- (T.1) *Control of slow-fast systems*. Metropolitan Autonomous University, Mexico City, Mexico, June 2018.
- (T.2) *Slow-fast systems beyond normal hyperbolicity*. Mexican Mathematicians in the World: Perspectives and Recent Contributions, BIRS-Oaxaca, June 2018.
- (T.3) *Normal forms of slow-fast systems*. Oberseminar, Technical University of Munich, April 2018.
- (T.4) *Slow-fast systems and constrained differential equations*. Metropolitan Autonomous University, Mexico City, Mexico, July 2016.
- (T.5) *Slow-fast systems and constrained differential equations*. TU Wien, Austria, April 2016.
- (T.6) *On A_k slow-fast systems*. “Advances in Qualitative Theory of Differential Equations”, Universitat Rovira i Virgili, Spain, 2015.
- (T.7) *Normal forms of constrained differential equations with 3 parameters*. Floris Takens seminar, Nov. 2013, University of Groningen.

Grants

01/2019 – 12/2020	Marie-Curie EuroTechPostdoc
03/2018 – 12/2019	Technical University Foundation Fellowship (TUFF) Technical University of Munich.
03/2017	Research Opportunities Week (ROW) Technical University of Munich.
2011 – 2015	CONACyT grant for PhD studies.
2008 – 2010	CONACyT grant for M.Sc studies.

Languages

Spanish (Mother tongue), English (Fluent), Dutch (Basic), German (Basic), French (Basic).

Computational skills

- Mathematical Software and Programming: Python, MatLab/Octave, Mathematica, Maple
- Operating Systems: MS Windows, Linux
- Text Processing : \LaTeX , MS Office
- CAD/CAM/CAE: SolidWorks, I-DEAS, ANSyS, AutoCAD

Teaching

At the University of Groningen

- Mechatronics (Bachelor Course, 2015-2016, 2016-2017 and 2017-2018)
- Signals and Systems (Bachelor Course, 2016)
- Modeling and Control of Complex Nonlinear Engineering Systems (Master Course, 2016)

2009-2011 at the National Polytechnic Institute (UPIITA-IPN, Mexico)

- Electric Machines (Bachelor Course, 1 term)
- Control of electric machines (Bachelor Course, 2 terms)
- Robotics 1 (Bachelor Course, 3 terms)
- Robotics 2 (Bachelor Course, 3 terms)

Supervision & Mentoring

Master thesis projects at the University of Groningen

- Tomoyuki van Ouwendorp. “Passivity analysis of a bursting neuron”. University of Groningen, 2016-2017.

Bachelor thesis projects at the University of Groningen

- Sharon Verhoeff. “Numerical methods for parametric resonance”, 2017.
- Casper Stork. “Model and simulation of a cantilever under parametric resonance”, 2017.
- Jorick Wold. “Finite Element Analysis of a piezoelectric cantilever under parametric resonance”, 2017.
- Martijn Kamphuis. “A port-Hamiltonian approach to Gas Metal Arc Welding”, 2017.
- Vincent Samallo. “Camera integration on a robotic system”, 2016.
- Thomas Wesselink. “Controlling a flexible-joint robot”, 2016.
- Renate Bijker. “Improvement of a wind farm operation strategy”, 2016.

Bachelor thesis projects at the National Polytechnic Institute (UPIITA-IPN, México)

- Erik Hutrón-Ramírez, Victor Hugo Perea-Rivera, and Jacobo de Jesús Romero-Anaya, “Prototipo de Sistema Modular Didáctico para el Aprendizaje de Tópicos de Ingeniería Mecatrónica”, 2010.
- Karla Vega-Espino, “Diseño, modelado y construcción de un brazo robótico antropomórfico didáctico de 6 grados de libertad”, 2011.
- Miguel Ochoa-Navarrete, “Incorporación de un control de velocidad a un Helicóptero de radio-control”, 2011.
- Johan Michele Martínez-García, “Vehículo autónomo seguidor de trayectoria variable”, 2011.
- Álvaro Fernando Becerril-Martínez, Adriana Dulce Gómez-Rosal, Mario Alberto Peña-Romo, and Juan Carlos Rodríguez-Esquivel, “Diseño, construcción y control del prototipo de un robot de 3 grados de libertad de arquitectura semi-abierta”, 2011.
- Armando Baca-Sánchez, Said Baños-Cuevas, and Jonatan Asbel Pastrana-Alcalá, “Prototipo Mecatrónico de Sistema CNC portátil para la manufactura de PCBs”, 2011.

Reviewing

Mathematical Reviews of the AMS • zbMATH • Applied Mathematics and Computation • International Journal of Robust and Nonlinear Control • European Journal of Control • Journal of Dynamical and Control Systems • Conference on Decision and Control • IEEE-LCSS